DEM Modeling: Lecture 01 Introduction

Sample Previous Projects

- Soft-particle DEM simulations of 2-D granular flow in a high-shear mixer
- A review of continuum hydrodynamics using molecular dynamics
- A 3-D analytical geometry based contact detection procedure for sphero-cylinder shaped bodies
- An algorithm for contact detection of cylindrical bodies
- Polygonal collision detection for DEM
- Discrete element modeling of a ball on a rotating plate
- A discrete element model for simulating fracture in solids

Project Report Outline

- Introduction
- Background
- Theory/Algorithm Description
- Implementation
- Results
- Conclusions
- References
- Tables
- Figures
- Appendices (derivations, codes, etc.)

Questions to Address

- Why use computational models?
- What is DEM?
- How is DEM different from other methods such as CFD and FEM?
- What are DEM's strengths and weaknesses?
- What will be discussed in this course?

Motivation for Computational Modeling

- Experimental measurements of particulate flows are often difficult or expensive to make
 - can't easily investigate internal structure
 - PEPT (Stewart *et al.*, 2001)
 - x-rays (Baxter *et al*., 1989)
 - nuclear magnetic resonance (NMR) / magnetic resonance imaging (MRI) (Nakagawa *et al.*, 1993)
 - γ-ray tomography (Langston *et al*., 1997)
 - radio pill (Dave *et al.*, 1998)
 - radioactive tracers (Larachi et al., 1995)
 - intrusive probes
 - "freezing" the system (Brone and Muzzio, 2000)

Motivation for Computational Modeling...

- Experimental measurements of particulate flows are often difficult or expensive to make...
 - observations at boundaries
 - behavior at boundaries isn't necessarily the same as the internal behavior, *e.g.* side-wall convection (video), packing structure



- some quantities are difficult to measure
 - *e.g.* inter-particle forces, coordination number, particle orientation and rotational speed

Motivation for Computational Modeling...

• Some environments and properties are difficult to investigate experimentally

- e.g., inter-particle friction, modified gravity

- Computer models can be used to overcome these difficulties; however, care must be taken to address the following
 - proper modeling of the physics
 - computational issues such as:
 - stability, accuracy, duration, storage
 - validation

Motivation for Computational Modeling...

- reduce the number of experiments
- optimize design and operating conditions; allow for more creative design
- computational models are well suited for parametric studies
- ⇒ "A case study of the economic benefit of the application of CFD in one chemical and engineered-material company over a six-year period conservatively estimated that the application of CFD generated approximately a six-fold return on the total investment in CFD." (Davidson, 2001)

- Two broad classes of approaches for modeling particulate materials
 - -continuum
 - -discrete

- Continuum Approach
 - treat as a continuous substance, ignore individual particles
 - assumes the length scale of importance >> particle length scale
 - apply conservation of mass, momentum, and energy to small regions of the material
 - also need constitutive relations that define a particular substance, e.g. how stress and strain (or strain rate) are related for that substance
 - e.g. Newtonian fluid behavior
 - constitutive laws for particulate materials are not widely agreed upon, hundreds have been proposed, most are phenomenological (for dense flows in particular) (Cundall, 2001)
 - several constitutive laws may be required to describe different regions of the flow
 - solve the resulting equations numerically using methods such as finite differences, finite volumes, or finite elements

- Continuum Approach...
 - not well suited to investigate phenomena occurring at the length scale of a particle diameter
 - some particulate system phenomena are highly dependent on particle level behavior, *e.g.* shear bands
 - best suited to investigate large scale systems, *e.g.* at the unit operation scale





Figure 1, Computational fluid dynamics (CFD) amsistem of a breely bubbling pas-fluidzed bed showing the growth in bubble size with beight in the bed. Real indicates regions where the solids baction approaches maximum packing, blue indicates regions with no solids.



- Discrete Approach
 - *e.g.*, the discrete element method (DEM)
 - models the behavior of individual particles
 - overall system behavior the result of individual interactions
 - examples include:
 - cellular automata (Baxter and Behringer, 1991)
 - Monte Carlo methods (Rosato et al., 1986)
 - hard-particle methods (Campbell and Brennen, 1982; Luding, 1995)
 - soft-particle methods (Cundall and Strack, 1979; Walton and Braun, 1986)
 - these methods are used in fields other than granular flows
 - traffic simulations, astronomy, computer networks, crowd dynamics, biosystems interactions, roller bearing dynamics

- Discrete Approach...
 - very good for investigating phenomena occurring at the length scale of a particle diameter
 - not well suited for modeling larger scale systems exactly
 - e.g. V_{system} = 1 L, d = 100 μ m \Rightarrow ~10⁸ particles
 - however, can use DEM to approximate system behavior and gain insight
 - need information at the particle scale, e.g. particle shape, particle-particle friction, particle mechanical properties, etc.





Issues to Consider

- Make sure the physical model is a good one
 - 2D/3D, viscous/inviscid, compressible/incompressible, laminar/turbulent, frictional/non-frictional, deformable/rigid, etc.
 - CFD/FEM: continuum methods not suited for phenomena occurring at a particle length scale
 - DEM: force models, particle shape, degree of deformation, number of particles
 - appropriate constitutive laws
 - appropriate boundary conditions
- Make sure the computational model is a good one
 - grid/element quality (discretization errors)
 - convergence criteria
 - time step / stiffness / model parameters
- Model validation

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